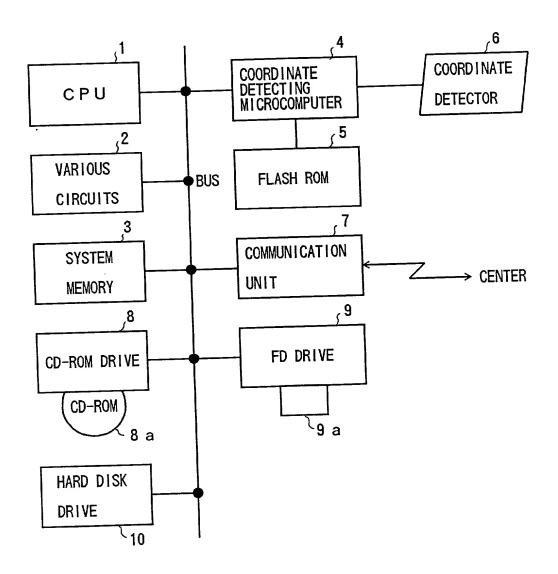
FIG. 1



F I G. 2

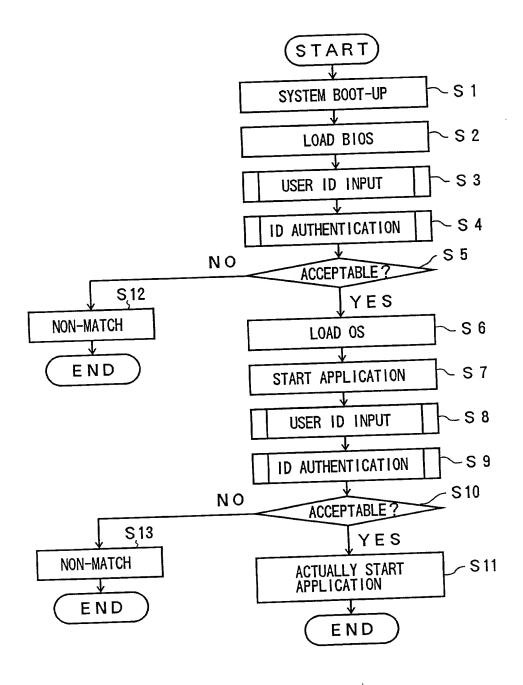


FIG. 3

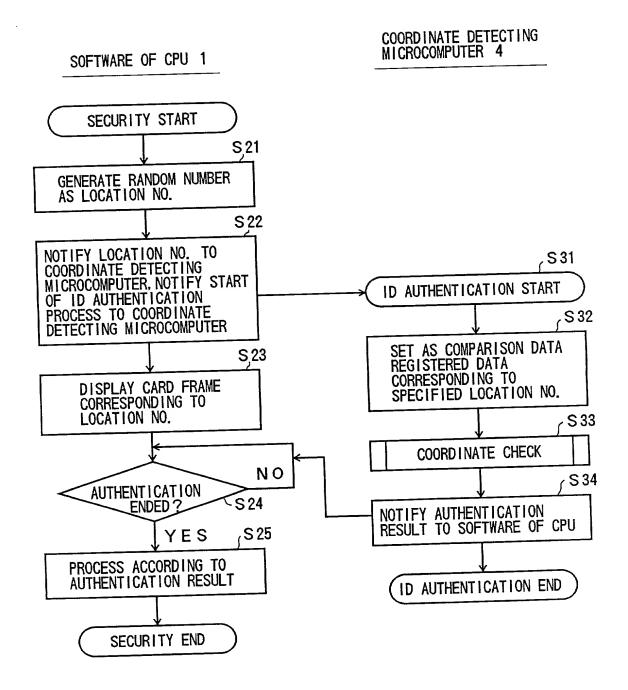


FIG. 4

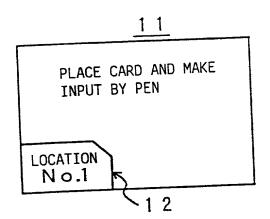


FIG. 5A

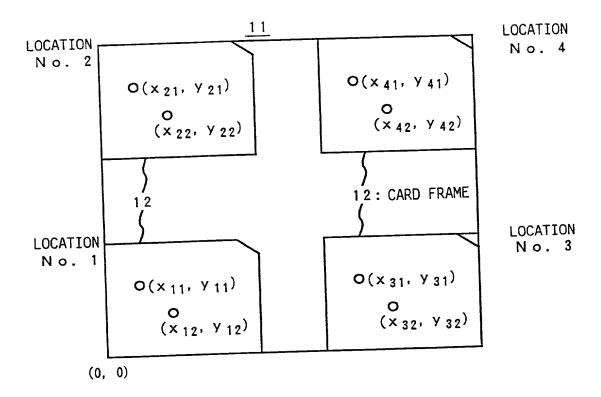


FIG. 5B

LC	CATION No.	POINT No.	COORDINATE
ſ		1	(x ₁₁ , y ₁₁)
	1	2	(x ₁₂ , y ₁₂)
		1	(x ₂₁ , y ₂₁)
	2	2	(x ₂₂ , y ₂₂)
		1	(x 31, y 31)
	3	2	(x 32, y 32)
		1	(x 41, Y 41)
	4	2	(x_{42}, y_{42})

FIG. 6A

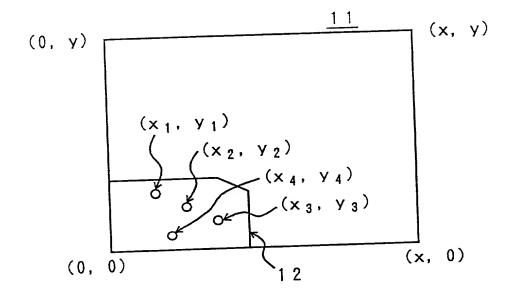


FIG. 6B

No.	COORDINATE
1	(x_1,y_1)
2	(x_2,y_2)
3	(x 3.y 3)
4	(x 4 . y 4)

F I G. 7

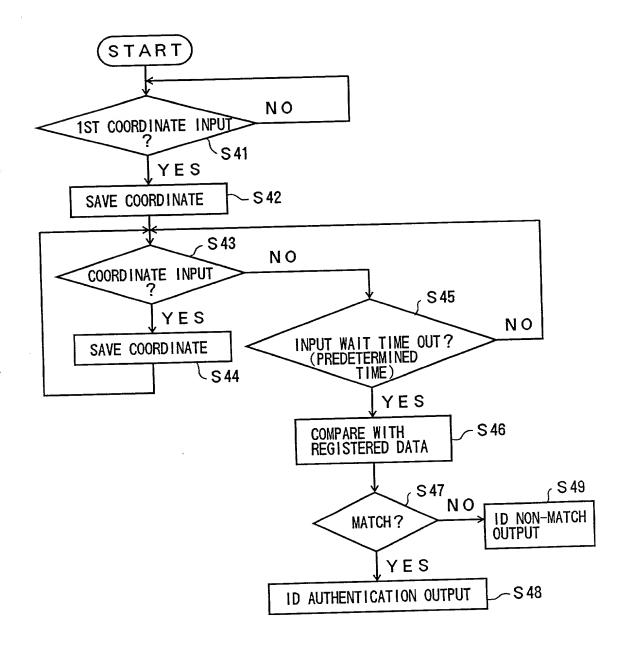


FIG. 8

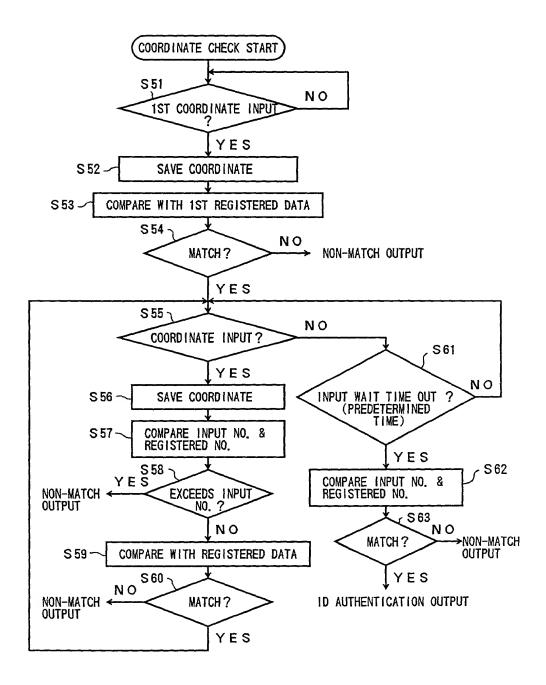


FIG. 9

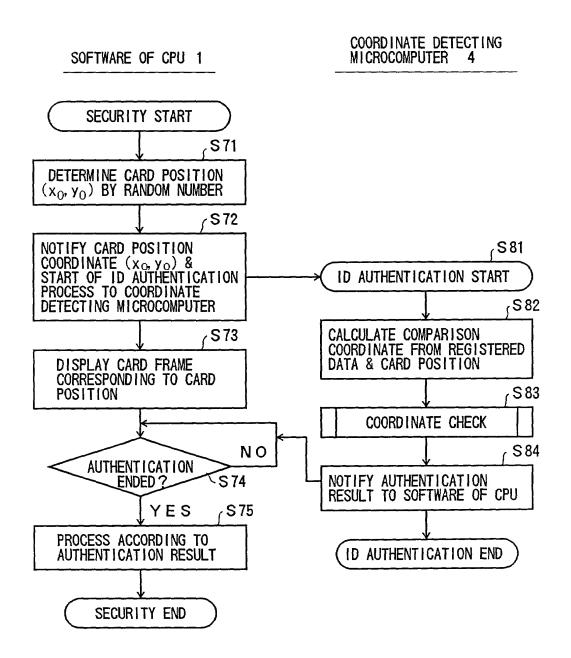
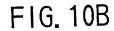
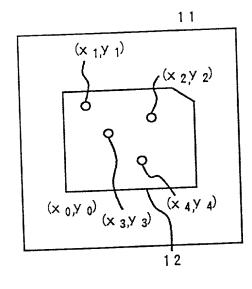


FIG. 10A





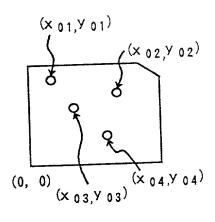
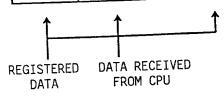


FIG. 10C

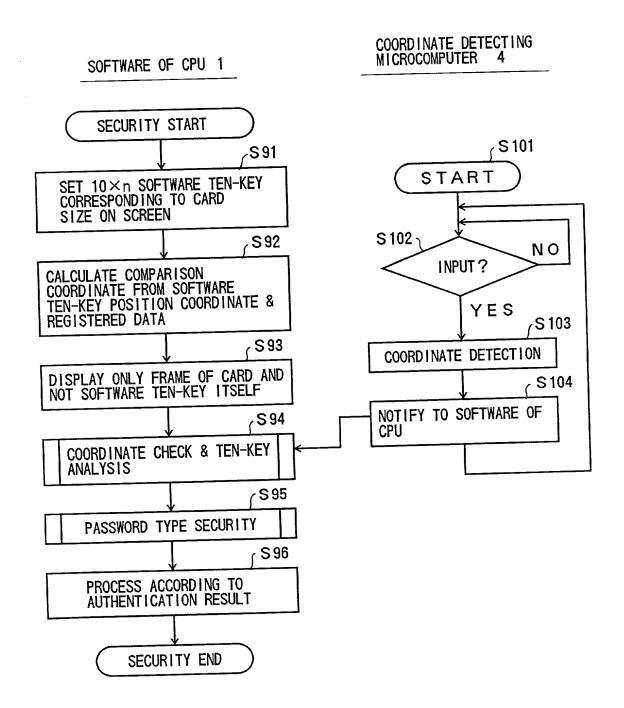
POINT No.	CARD ORIGIN	HOLE COORDINATE VALUE WITHIN CARD	
1	(× 0, y 0)	(x ₀₁ ,y ₀₁)	$(x_{1},y_{1}) = (x_{0}+x_{01}, y_{0}+y_{01})$
	(24 012 02	(x 02.y 02)	$(x_2, y_2) = (x_0 + x_{02}, y_0 + y_{02})$
2		(x 03, y 03)	$(x_3,y_3) = (x_0+x_{03}, y_0+y_{03})$
3			$(x_4,y_4) = (x_0+x_0, y_0+y_0)$
4		(x_{04}, y_{04})	CC 4,7 42 CC 0 C4

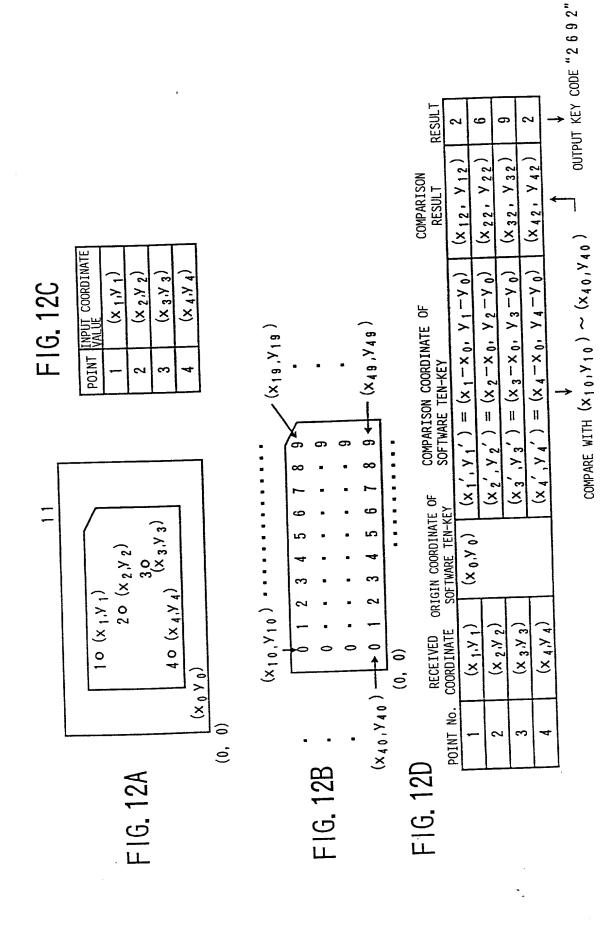


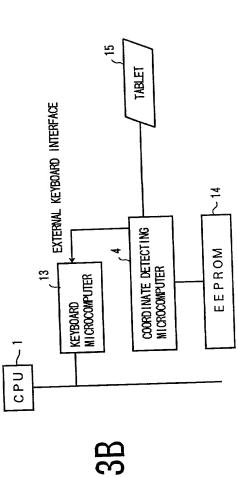
OBTAIN DATA FOR COMPARISON WITH ACTUALLY DETECTED COORDINATE FOR AUTHENTICATION BY CALCULATION PRIOR TO AUTHENTICATION

11

FIG. 11







F16. 13B

FIG. 14

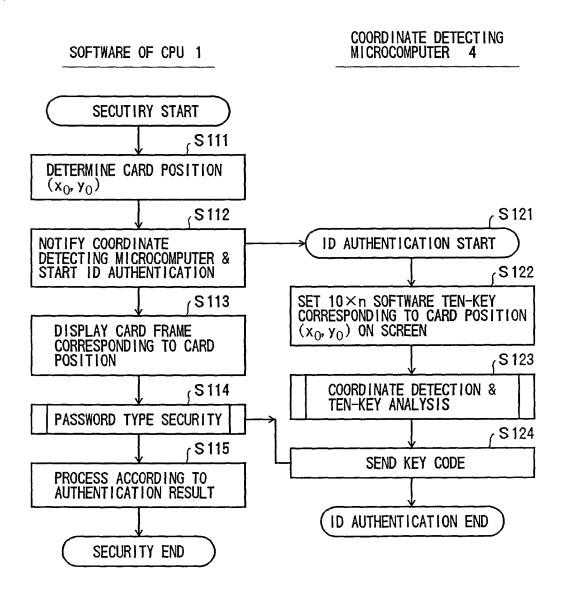
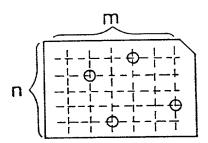


FIG. 15A



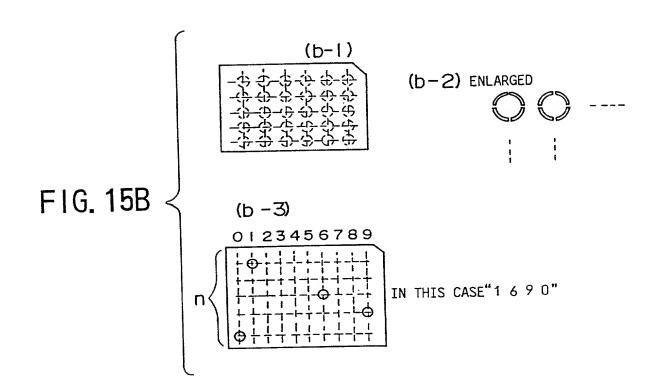


FIG. 16

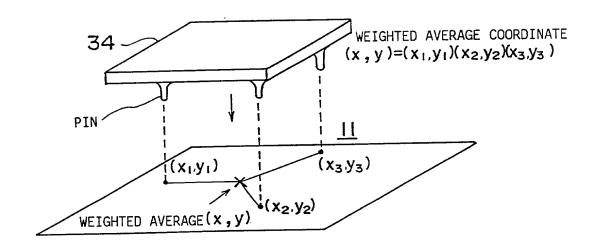


FIG. 17

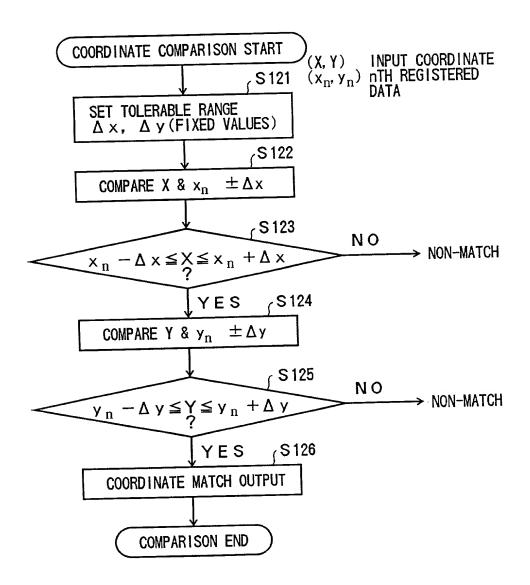


FIG. 18A

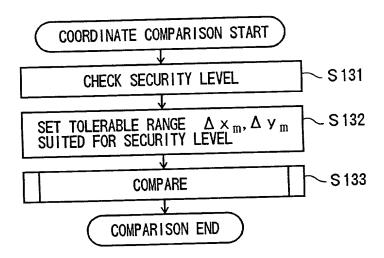


FIG. 18B

	SECURITY LEVEL	TOLERABLE RANGE
	1	$(\Delta x_1, \Delta y_1)$
	m	$(\Delta x_m, \Delta y_m)$
	Q.	$(\Delta \times_{\ell}, \Delta y_{\ell})$
WH	HERE $\Delta \times_1$ $\Delta \times_1$	>> \(\times x \) \(\times

F1G. 19A

		REGISTERED DATA	COMPARISON COORDINATE RANGE
POINT NO.	CARD ORIGIN	OF HOLE COORDINATES WITHIN CARD	min
-		(× ₀₁ y ₀₁)	$(x_0 - \Delta x_0 + x_{01}, y_0 - \Delta y_0 + y_{01})$
2	(x0 y0)	(× 02 V 02)	$(x_0 - \Delta x_0 + x_{02}, y_0 - \Delta y_0 + y_{02})$
3	TOLERABLE RANGE	(× 03 × 03)	$(x_0 - \Delta x_0 + x_{03}, y_0 - \Delta y_0 + y_{03})$
4	(\(\nabla \) \((× 04 Y 04)	$(x_0 - \Delta x_0 + x_{04}, y_0 - \Delta y_0 + y_{04})$

max $(x_0 + \Delta x_0 + x_{01}, y_0 + \Delta y_0 + y_{01})$ $(x_0 + \Delta x_0 + x_{02}, y_0 + \Delta y_0 + y_{02})$ $(x_0 + \Delta x_0 + x_{02}, y_0 + \Delta y_0 + y_{03})$ $(x_0 + \Delta x_0 + x_{03}, y_0 + \Delta y_0 + y_{03})$ $(x_0 + \Delta x_0 + x_{04}, y_0 + \Delta y_0 + y_{04})$

F16, 19B

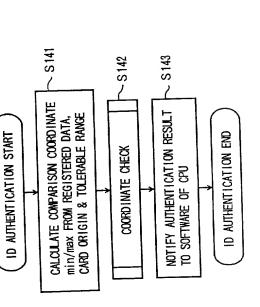


FIG. 20

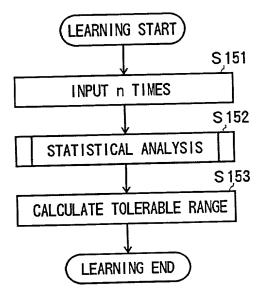


FIG. 21

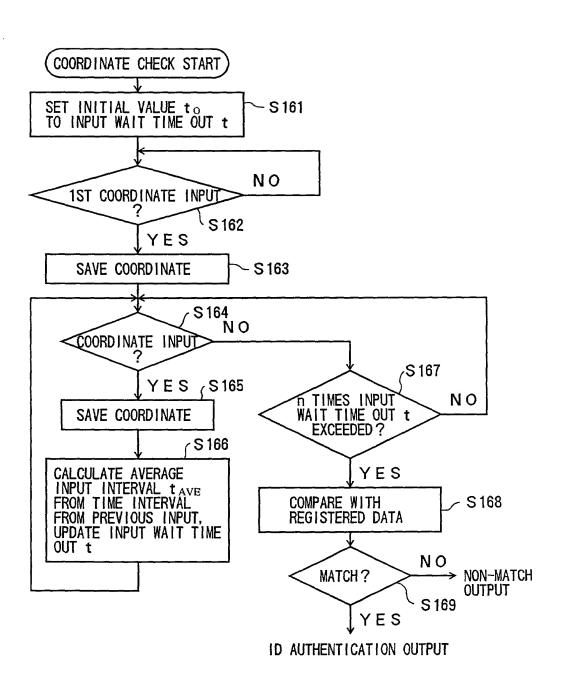


FIG. 22

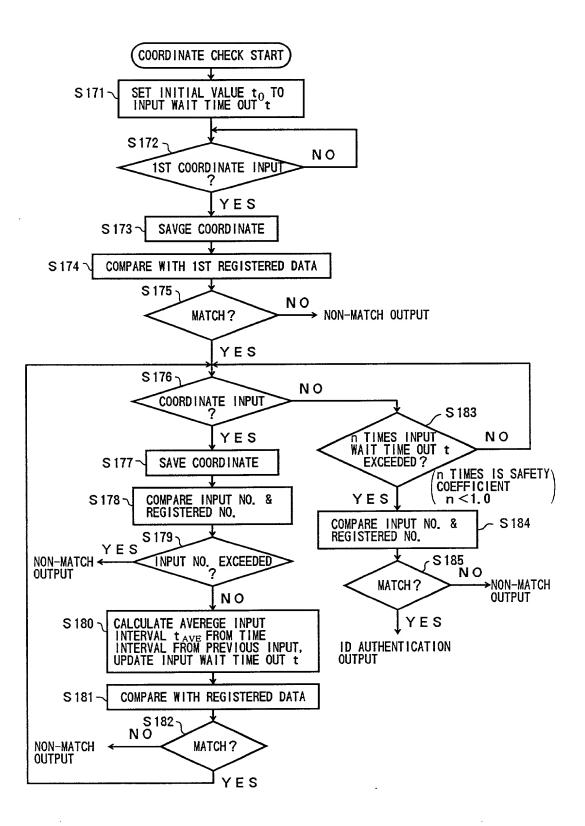
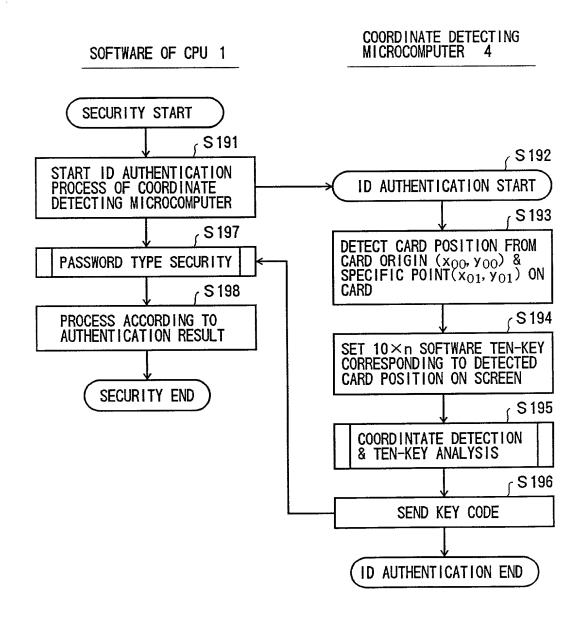
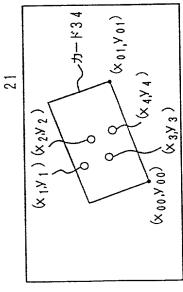


FIG. 23





F16, 24A

		1
NT DETECTED	CARD POSITION	
COODITINATE	DETECTION COODIINATE	COMPAR

TEN-KEY	COMPARISON COORDINATE
SOFTWARE	COMPARISON

COMPARISON RESULT	(× _{12,} y ₁₂)
SOFTWARE TEN-KEY COMPARISON COORDINATE	(A) 200, VIII A) (1, V, I) (1, V, I)
OSITION	(00)

F16, 24B

ERICAL UE		····		
VALUE	7	9	6	2
COMPARISON NUMERICAL RESULT VALUE	(x ₁₂ ,y ₁₂) 2	(×22,Y22) 6	(×32, y32) 9	(x 42, y 42) 2
SOFTWARE TEN-KEY COMPARISON COORDINATE	(x_1', y_1') = $(x_{00}' x_1 \cos \Delta \theta - y_1 \sin \Delta \theta_1 y_{00}' x_1 \sin \Delta \theta + y_1 \cos \Delta \theta)$	$\frac{(x_2', y_2')}{\ell_n} = \frac{(x_2', y_2')}{(x_2 \cos \Delta \theta - y_2 \sin \Delta \theta, y_{00}' \times 2 \sin \Delta \theta + y_2 \cos \Delta \theta)}$	$\frac{(x_3', y_3')}{\ell_0} = \frac{(x_3', y_3')}{(x_3' \cos \Delta \theta - y_3 \sin \Delta \theta, y_{00}' \times 3 \sin \Delta \theta + y_3 \cos \Delta \theta)}$	4 (x_4, y_4) ℓ_0 : DISTANCE BETWEEN (x_4', y_4') ℓ_0 : POSITIONING HOLES (x_4, y_4') (x_4, y_4)
CARD POSITION DETECTION COORDINATE	(x 00, V 00)	$2 \left(\frac{\sqrt{2}}{2} \right) \sin \Delta \theta = \frac{\sqrt{01 - \sqrt{00}}}{\ell}$	×	2 0: DISTANCE BETWEEN
POINT DETECTED No. COORDINATE	(×1,Y1)	(x ₂ y ₂)	$3 \left(\times_3 y_3 \right) \cos \Delta \theta =$	(x 4, y 4)
INT .		2	3	4
8 8				

FIG. 25

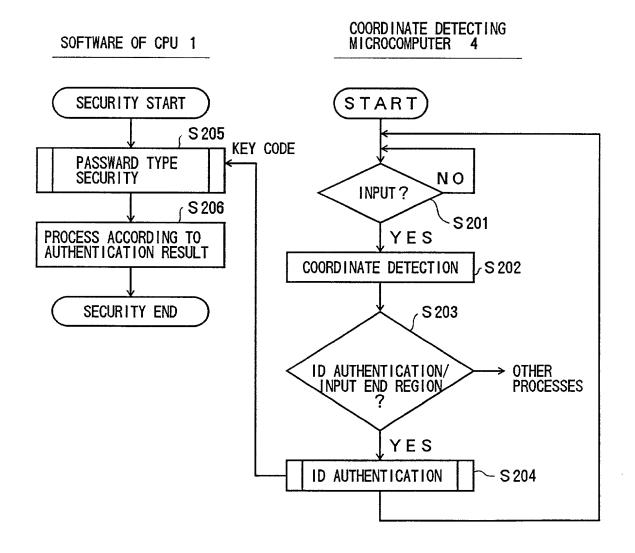


FIG. 26

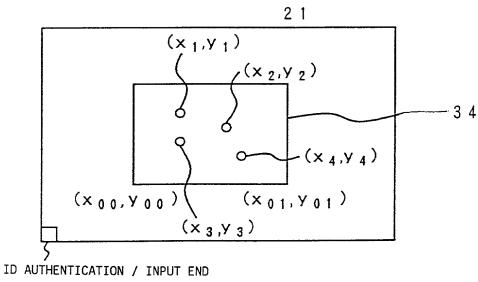
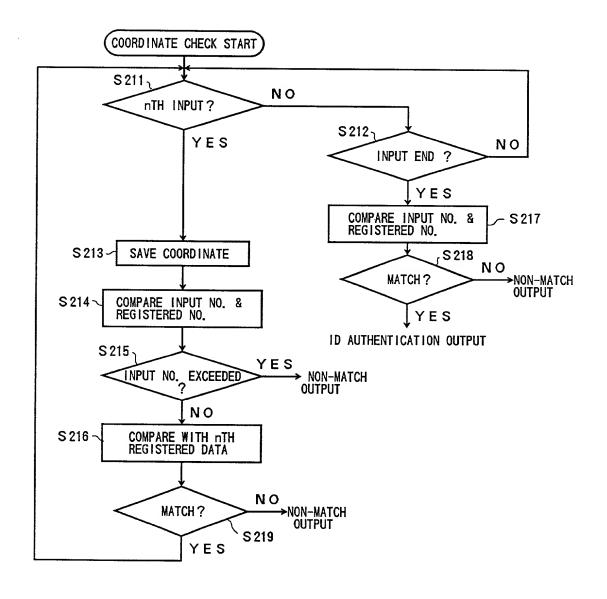


FIG. 27



F1G. 28

8 8 N	POINT DETECTED NO. COORDINATE	CARD POSITION E DETECTION COORDINATE	TE COMPARISON COORDINATE	REGISTERED COORDINATE	OUTPUT KEY CODE AFTER ID AUTHENT!CATION	R ID
	(x1 y1)	$(x_1 y_1) (x_{00} y_{00})$	$(x_1, y_1) = (x_{00} + x_1 \cos \Delta \theta - y_1 \sin \Delta \theta, y_{00} + x_1 \sin \Delta \theta + y_1 \cos \Delta \theta)(x_1, Y_1)$	θ)(×1, Υ ₁)	2	
2	2 (x ₂ y ₂)	$\sin \Delta \theta = \frac{y_{01} - y_{00}}{a}$	$(x_2, y_2') = (x_{00} + x_2 \cos \Delta \theta - y_2 \sin \Delta \theta, y_{00} + x_2 \sin \Delta \theta + y_2 \cos \Delta \theta)(x_2, Y_2)$	θ)(x ₂ , Y ₂)	9	
က	(x3 y3)	$\cos \Delta \theta = \frac{\text{Y or } - \text{Y or}}{\text{A}}$	$(x_3, y_3') = (x_{00} + x_3\cos\Delta\theta - y_3\sin\Delta\theta, y_{00} + x_3\sin\Delta\theta + y_3\cos\Delta\theta)(x_3, Y_3)$	θ)(x ₃ , Y ₃)	6	
4	(x4 y4)	4 $(x_4 y_4)$ ℓ_0 :DISTANCE BETWEEN POSITIONING HOLES	$(x_4' y_4') = (x_{00} + x_4 \cos \Delta \theta - y_4 \sin \Delta \theta, y_{00} + x_4 \sin \Delta \theta + y_4 \cos \Delta \theta)(x_4, Y_4)$	θ)(×4, Υ ₄)	2	

FIG. 29

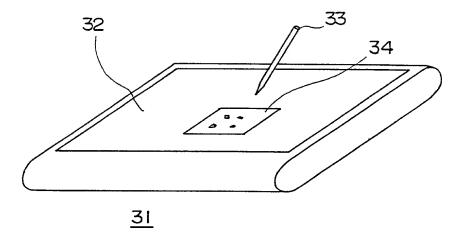
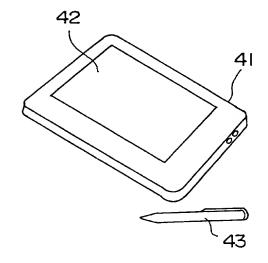
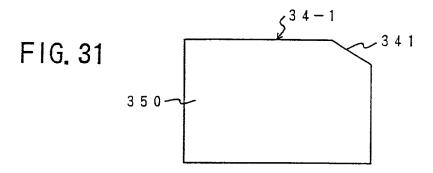


FIG. 30





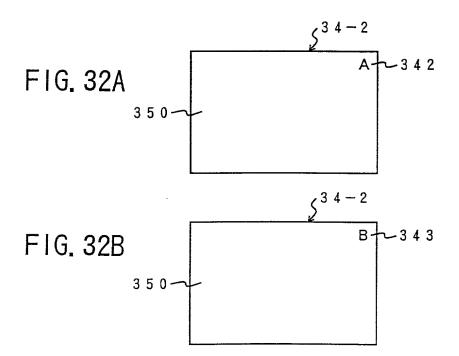


FIG. 33

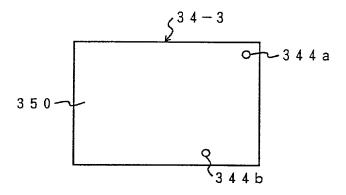


FIG. 34

